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ABSTRACT OF THE DISCLOSURE

A system and a method for low speed collision avoidance by a vehicle are provided. The low speed collision avoidance system includes an operation control module in communication with a plurality of signal generators for determining a distance to an object, a vehicle velocity, an accelerator position, a brake switch position and a shift position to effect vehicle operation. The system and the method for low speed collision avoidance operate when the vehicle is traveling below a predetermined low velocity and when the vehicle is stopped.